

Generate Glacier Velocity Maps with the Sentinel-1 Toolbox

Adapted from the European Space Agency's <u>STEP</u> community platform

In this document you will find:

- A. System Requirements
- B. Background
- C. Materials List
- D. Steps to Generate Glacier Velocity Map
- E. Sample Image

A) System Requirements

Many of the steps within this data recipe may take some time to process. We recommend the following:

- At least 16GB memory (RAM)
- Close other applications if possible while using S1TBX
- Do not use the computer during processing to avoid crashes

B) Background

The goal of this tutorial is to provide novice and experienced remote sensing users with step-by-step instructions on the use of Offset Tracking tools in generating glacier velocity maps with Sentinel-1 Level-1 Ground Range Detected (GRD) products. Offset Tracking is a technique that measures feature motion between two images using patch intensity cross-correlation optimization. It is widely used in glacier motion estimation.

Level-1 Ground Range Detected (GRD) products consist of focused SAR data that has been detected, multi-looked and projected to ground range using an Earth ellipsoid model such as WGS84. The ellipsoid projection of the GRD products is corrected using the terrain height specified in the product general annotation. The terrain height used varies in azimuth but is constant in range.

This tutorial will examine the movement of the Rink glacier. Rink glacier is a large glacier located on the west coast of Greenland. It drains an area of 30,182 km2 (11,653 sq mi) of the Greenland ice sheet with a flux (quantity of ice moved from the land to the sea) of 12.1 km3 (2.9 cu mi) per year, as measured for 1996. It is also the swiftest moving and highest surface ice in the world.



Figure 1-A: Rink Glacier in Google Maps



Figure 1-B: Rink Glacier calving; Credit: Faezeh M. Nick

C) Materials List

- Windows, Mac OS X, Unix
- <u>Sentinel-1 Toolbox</u> (version 5.0 was used in this recipe)

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UAF is an AA/EO employer and educational institution and prohibits illegal discrimination against any individual: www.alaska.edu/nondiscrimination Pair of Sentinel-1 IW GRD products. Either download the sample granules below or use the <u>Vertex</u> data portal to download your own GRD products.

<u>S1A_IW_GRDH_1SSH_20160708T204736_20160708T204801_012062_012A6D_D116</u>
 <u>S1A_IW_GRDH_1SSH_20160720T204737_20160720T204802_012237_013014_9C25</u>

Note: The input products should be two GRD products over the same area acquired at different times. The time interval should be as short as possible. In this tutorial, we will use the following two GRD products acquired 12 days apart.

D) Steps to Generate Glacier Velocity Map

Step 1: Open the products in S1TBX

- a) Open the Sentinel-1 Toolbox software
- b) Use the **Open Product** button in the top toolbar and browse to the location of the two GRD products
- c) Press and hold the Ctrl button to select both *.zip* files and press **Open**

Note: Do not extract the files, S1TBX will do so automatically when the files are loaded into the program. If you unzipped the files, select the *manifest.safe* file from each Sentinel-1 product folder.

Step 2: View the products

- a) In the **Products Explorer** you will see the opened products
- b) Double-click on the product to expand (Figure 2)
- c) Expand the bands folder and you will find two bands: an *amplitude* band, which is actually the product, and a virtual *intensity* band, which is there to assist you in working with the GRD data.
- d) To view the data, double-click on the **Amplitude_HH** band (Figure 3)
- e) Zoom in using the mouse wheel and pan by clicking and dragging the left mouse button



Figure 1: Products Explorer with World View

Continued on the next page...



Figure 2: Amplitude_HH Band of Product [1]

Comparing this image to the world map in Figure 2, you will find that the image is flipped upside-down. This is because the image was acquired with an ascending pass and right-pointing antenna. Therefore, the bottom part of the image area was first sensed and in S1TBX, the first sensed line is always displayed on top of the image.

Step 3: Apply orbit file

- a) Select GRD product in the Product Explorer window
- b) From the top menu navigate to *Radar > Apply Orbit File*
- c) In the *Apply-Orbit-File* window (Figure 3), specify the output folder and the target product name. The products will automatically be appended with the suffix "**Orb**" if you choose the default name.
- d) Leave all default parameters and click Run
- e) Repeat steps a) d) for the second GRD product
- f) When finished, close the Apply-Orbit-File window



	Apply Orbit File
File He	2
	I/O Parameters Processing Parameters
Orbit St	ite Vectors: Sentinel Precise (Auto Download) 🔷 ᅌ
Polynor	ial Degree: 3
	Do not fail if new orbit file is not found
	Run Close

Figure 3: Apply Orbit File dialog

Step 4: Coregister the images into a stack using DEM

From the top menu navigate to Radar > Coregistration > DEM Assisted Coregistration and select DEM Assisted Coregistration with XCorr a)

a) In the *ProductSet-Reader* tab (Figure 4.1), press the "+" button to add the products, ensuring that the older product is selected first

ProductSet-Reader	DEM-Assisted-Coregistration	Cross-Correlation	Warp	Write
File Name S1A IW CRDH 15SH 20	1607087204736 2016070872048	01 012062 01246		÷
51A_IW_GRDH_155H_201	160720T204737_20160720T2048	02_012237_013014	2	4
				-
				*
				-
				2
				8
				2 Products

Figure 4.1: DEM Assisted Coregistration with paired products

 b) In the *DEM-Assisted-Coregistration* tab (Figure 4.2), select the **Digital Elevation** Model (DEM) to use, the **DEM resampling method**, and image resampling method.

	DEM Assis	ted Coregistration	with XCorr		
ProductSet-Reader	DEM-Assisted	-Coregistration	Cross-Correlation	Warp	Write
Digital Elevation Model	:	ACE30 (Auto Do	ownload)		0
DEM Resampling Method: Resampling Type: Tile Extension [%]:		BILINEAR_INTER	POLATION		0
		BILINEAR_INTER	POLATION		0
		100			
✓ Mask out areas wit	h no elevation				
		🕐 Help 🕞 Run			

Figure 4.2: DEM Assisted Coregistration with DEM selected

Note: The default DEM is *SRTM 3 Sec*, which covers most area of the earth's surface between –60 degree latitude and +60 degree latitude. However, it does not cover the high latitude area where Rink Glacier is located. Therefore, *ASTER GDEM, GETASSE30 or ACE30 DEM* could be selected. Areas outside the DEM or in the sea may be optionally masked out.

- c) In the *Write* tab and specify the output folder and the target product name. The product will automatically be appended with the suffix "**Stack**" if you choose the default name.
- d) Leave all other parameters as default and click Run
- e) When finished, close the Coregistration window

v ()	[1] S1A_IW_GRDH_1SSH_20160708T204736_20160708T204801_012062_012A6D_D116_Orb_Stack
►	🗋 Metadata
►	🔄 Vector Data
►	Tie-Point Grids
	🔄 Bands
	Amplitude_HH_mst_08Jul2016
	Amplitude_HH_slv1_20Jul2016

Figure 5: Coregistered stack product

Step 5: Create subset image containing Rink Glacier

Since the image covers a large area of the west coast of Greenland and we are interested only in the Rink Glacier area, we will create a subset of the coregistered stack that contains the Rink Glacier area only. See Figure 6 below.

- a) Open one of the bands from your *coregistered* stack
- b) Zoom in the image until the image window contains only the area of interest
- c) Right-click on the image and select **Spatial Subset** from View...
- d) When the *Specify Product Subset* window appears, click **OK** to create subset
- e) Save the newly created subset product by right-clicking on the product in the **Product Explorer** and select **Save Product**

Geometry from WKT

WKT from Geometry Export Transect Pixels Export Mask Pixels Export View as Google Earth KMZ Export View as Image Export Colour Palette as File Export Colour Legend as Image Spatial Subset from View... Copy Pixel-Info to Clipboard



Figure 6: Subset area in the image

Offset Tracking

The Offset Tracking operator estimates the movement of glacier surfaces between master and slave images in both slant-range and azimuth direction. It performs cross-correlation on selected Ground Control Point (GCP) in master and slave images. Then the glacier velocities on the selected GCPs are computed based on the offsets estimated by the cross-correlation. Finally, the glacier velocity map is generated through interpolation of the velocities computed on the GCP grid. The Offset Tracking is performed in the following sub-steps:

- 1. For each point in the user specified GCP grid in master image, compute its corresponding pixel position in slave image using normalized cross-correlation.
- 2. If the compute offset between master and slave GCP positions exceeds the maximum offset (computed from user specified maximum velocity), then the GCP point is marked as outlier.
- 3. Perform local average for the offset on valid GCP points.
- 4. Fill holes caused by the outliers. The offset at a hole-point will be replaced by a new offset computed by local weighted average.
- 5. Compute the velocities for all points on GCP grid from their offsets.
- 6. Finally, compute velocities for all pixels in the master image from the velocities on GCP grid by interpolation.

In the Offset Tracking dialog window (Figure 7), user needs to define a GCP grid by specifying the grid point spacing in range and azimuth directions. The spacing is specified in term of the number of pixels. Then the system will convert the spacing into corresponding spacing in meters and compute the grid dimension.

The user also needs to specify other processing parameters such as Registration Window dimension and Maximum Velocity. Before running the operator, the user is suggested to do some research on the maximum velocity of the glacier under study on the season of acquisition. This will be helpful in guiding the user selecting meaningful processing parameters. For example, the maximum velocity for Rink Glacier is around 10 meters per day. Given that the SAR image acquisition period is 12 days and range and azimuth spacing is 10 meters, we can calculate the maximum shift of a target in the glacier is about 12 pixel. We know that the default Registration Window dimension (128 pixels) is larger enough to cover the target in both master and slave images.

The Spatial Average and Fill Holes processing steps can be optionally turned off by deselecting the corresponding checkboxes in the dialog window.

Step 6: Generate glacier velocity map

- a) Navigate to Radar > SAR Applications > Offset Tracking from the top menu
- b) Select your subset image as the source product
- c) Specify the output folder and the target product name. The product will automatically be appended with the suffix "_Vel" if you choose the default name.
- d) In the Processing Parameters tab (Figure 7), change Max Velocity (m/day): to "10"
- e) Leave all other default parameters and click Run

	I/O Par	rameters	Processing Parameters	
Output Grid Grid Azimuth Spacing (in Grid Range Spacing (in pi Grid Azimuth Spacing (in Grid Range Spacing (in m Grid Azimuth Dimension: Grid Range Dimension:	pixels): xels): meters): eters):	40 40 400.0 400.0 64 87	Registration Registration Window Width: Registration Window Height: Cross-Correlation Threshold: Average Box Size: Max Velocity (m/day): Radius for Hole Filling:	128 C 128 C 0.1 5 C 10.0 4
Resampling Type:		5568	BICUBIC INTERPOLATION	
ROI Vector Mask:			 ✓ Spatial Average ✓ Fill Holes 	

Figure 7: Offset Tracking dialog

Step 7: View the glacier velocity map

a) Double-click on the *velocity* band in the resulting product to display the velocity map (Figure 8)



Figure 8: Velocity Map of Rink Glacier; Contains modified Copernicus Sentinel data

- b) Navigate to Layer > Layer Manager
- c) From the Layer Manager window, deselect Vector data to remove the grid
- d) Click on the "+" button to open the Add Layer window
- e) In the Add Layer window (Figure 9), click **Coregistered GCP Movement Vector** and click on **Finish**. You will see the velocity vectors displayed on the GCP grid showing direction and speed (Figure 10)



Figure 9: Add Layer dialog

F) Sample Image



Figure 10: Velocity vectors on GCP grid; Contains modified Copernicus Sentinel data